CS425 Lab: Frequency Domain Processing

1. Discrete Fourier Transform

See section 14.1 in your textbook

This is a brief review of the Fourier transform. An in-depth discussion of the Fourier transform is best left to your class instructor.

The general idea is that the image (f(x,y)) of size $M \times N$) will be represented in the frequency domain (F(u,v)). The equation for the two-dimensional discrete Fourier transform (DFT) is:

$$F(u,v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) e^{-i2\pi \left(\frac{ux}{M} + \frac{vy}{N}\right)}$$

The concept behind the Fourier transform is that any waveform can be constructed using a sum of sine and cosine waves of different frequencies. The exponential in the above formula can be expanded into sines and cosines with the variables \boldsymbol{u} and \boldsymbol{v} determining these frequencies.

The inverse of the above discrete Fourier transform is given by the following equation:

$$f(x,y) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u,v) e^{i2\pi \left(\frac{ux}{M} + \frac{vy}{N}\right)}$$

Thus, if we have F(u,v), we can obtain the corresponding image (f(x,y)) using the inverse, discrete Fourier transform.

Things to note about the discrete Fourier transform are the following:

the value of the transform at the origin of the frequency domain, at F(0,0), is called the dc component

- o F(0,0) is equal to MN times the average value of f(x,y)
- o in MATLAB, F(0,0) is actually F(1,1) because array indices in MATLAB start at 1 rather than 0

the values of the Fourier transform are complex, meaning they have real and imaginary parts. The imaginary parts are represented by i, which is defined solely by the property that its square is −1, ie:

$$i^2 = -1$$

we visually analyze a Fourier transform by computing a **Fourier spectrum** (the magnitude of F(u,v)) and display it as an image.

o the Fourier spectrum is symmetric about the origin

the fast Fourier transform (FFT) is a fast algorithm for computing the discrete Fourier transform.

MATLAB has three functions to compute the DFT:

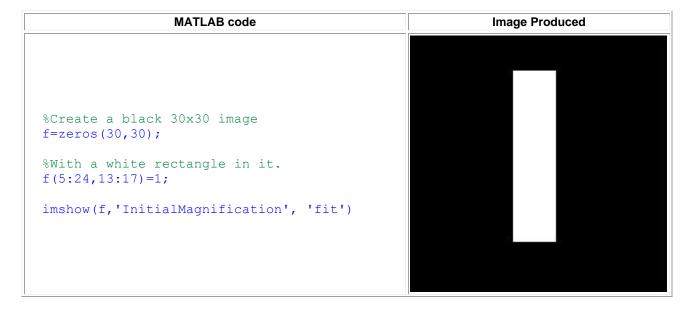
- 1. fft -for one dimension (useful for audio)
- 2. fft2 -for two dimensions (useful for images)
- 3. fftn -for n dimensions

MATLAB has three related functions that compute the inverse DFT:

- 0. ifft
- **1.** ifft2
- 2. ifftn

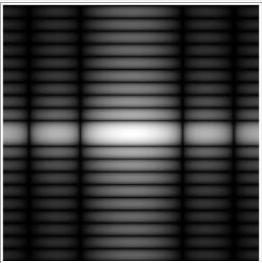
1.1 How to Display a Fourier Spectrum using MATLAB

The following table is meant to describe the various steps behind displaying the Fourier Spectrum.



```
%Calculate the DFT.
F=fft2(f);
%There are real and imaginary parts to F.
%Use the abs function to compute the
magnitude
%of the combined components.
F2=abs(F);
figure, imshow(F2,[],
'InitialMagnification','fit')
\ensuremath{\,^{\circ}} To create a finer sampling of the Fourier
transform,
%you can add zero padding to f when
computing its DFT
%Also note that we use a power of 2, 2^256
%This isbecause the FFT -Fast Fourier
Transform -
%is fastest when the image size has many
factors.
F=fft2(f, 256, 256);
F2=abs(F);
figure, imshow(F2, [])
%The zero-frequency coefficient is
displayed in the
%upper left hand corner. To display it in
the center,
%you can use the function fftshift.
F2=fftshift(F);
F2=abs(F2);
figure, imshow(F2,[])
```

```
%In Fourier transforms, high peaks are so high they %hide details. Reduce contrast with the log function. F2=log(1+F2); figure,imshow(F2,[])
```



To get the results shown in the last image of the table, you can also combine MATLAB calls as in:

```
f=zeros(30,30);
f(5:24,13:17)=1;
F=fft2(f, 256,256);
F2=fftshift(F);
figure,imshow(log(1+abs(F2)),[])
```

Notice in these calls to imshow, the second argument is empty square brackets. This maps the minimum value in the image to black and the maximum value in the image to white.

2. Frequency Domain Versions of Spatial Filters

See section 14.3.5, 14.5.1, and 14.5.2 in your textbook

The following convolution theorem shows an interesting relationship between the spatial domain and frequency domain:

$$f(x,y)*h(x,y) \Leftrightarrow H(u,v)F(u,v)$$

and, conversely,

$$f(x,y)h(x,y) \Leftrightarrow H(u,v)*G(u,v)$$

where the symbol "*" indicates convolution of the two functions. The important thing to extract out of this is that the multiplication of two Fourier transforms corresponds to the convolution of the associated functions in the spatial domain. This means we can

perform linear spatial filters as a simple component-wise multiply in the frequency domain.

This suggests that we could use Fourier transforms to speed up spatial filters. This only works for large images that are correctly padded, where multiple transformations are applied in the frequency domain before moving back to the spatial domain.

When applying Fourier transforms padding is very important. Note that, because images are infinitely tiled in the frequency domain, filtering produces wraparound artefacts if you don't zero pad the image to a larger size. The paddedsize function below calculates a correct padding size to avoid this problem. The paddedsize function can also help optimize the performance of the DFT by providing power of 2 padding sizes. See paddesize's help header for details on how to do this.

2.1 Basic Steps in DFT Filtering

The following summarize the basic steps in DFT Filtering (taken directly from page 121 of *Digital Image Processing Using MATLAB*):

- Obtain the padding parameters using function <u>paddedsize</u>: PQ=paddedsize(size(f));
- 2. Obtain the Fourier transform of the image with padding: F=fft2(f, PQ(1), PQ(2));
- 3. Generate a filter function, H, the same size as the image
- 4. Multiply the transformed image by the filter: G=H.*F;
- 5. Obtain the real part of the inverse FFT of G: g=real (ifft2 (G));
- 6. Crop the top, left rectangle to the original size: g=g(1:size(f, 1), 1:size(f, 2));

2.2 Example: Applying the Sobel Filter in the Frequency Domain

For example, let's apply the Sobel filter to the following picture in both the spatial domain and frequency domain.

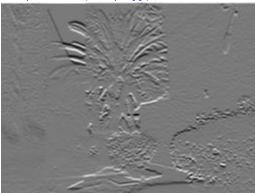


*Note, this code relies on paddedsize.m

Spatial Domain Filtering

%Create the Spacial Filtered Image f = imread('entry2.png'); h = fspecial('sobel'); sfi = imfilter(double(f),h, 0, 'conv');

%Display results (show all values)
figure,imshow(sfi, []);

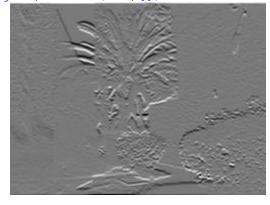


%The abs function gets correct
magnitude
%when used on complex numbers
sfim = abs(sfi);
figure, imshow(sfim, []);

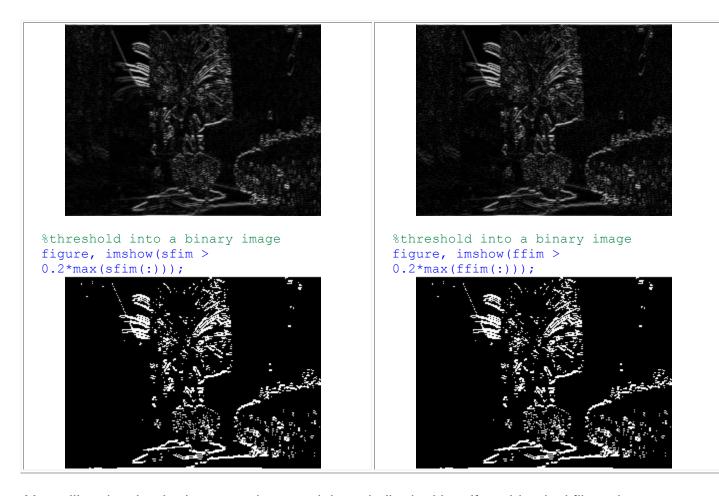
Frequency Domain Filtering

```
%Create the Frequency Filtered Image
f = imread('entry2.png');
h = fspecial('sobel');
PQ = paddedsize(size(f));
F = fft2(double(f), PQ(1), PQ(2));
H = fft2(double(h), PQ(1), PQ(2));
F_fH = H.*F;
ffi = ifft2(F_fH);
ffi = ffi(2:size(f,1)+1,
2:size(f,2)+1);
```

%Display results (show all values)
figure, imshow(ffi,[])



%The abs function gets correct
magnitude
%when used on complex numbers
ffim = abs(ffi);
figure, imshow(ffim, []);



You will notice that both approaches result in a similar looking, if not identical filtered image. You may have to adjust how you crop the image slightly as shown in the example above.

3. Frequency Domain Specific Filters

See section 14.5.3 in your textbook, and Chapter 4 and Section 5.4 in Digital Image Processing Using MATLAB

As you have already seen, based on the property that multiplying the FFT of two functions from the spatial domain produces the convolution of those functions, you can use Fourier transforms as a fast convolution on large images. Note that on small images it is faster to work in the spatial domain.

However, you can also create filters directly in the frequency domain. There are three commonly discussed filters in the frequency domain:

Lowpass filters, sometimes known as smoothing filters Highpass filters, sometimes known as sharpening filters Notch filters, sometimes known as band-stop filters

3.1 Lowpass Filters

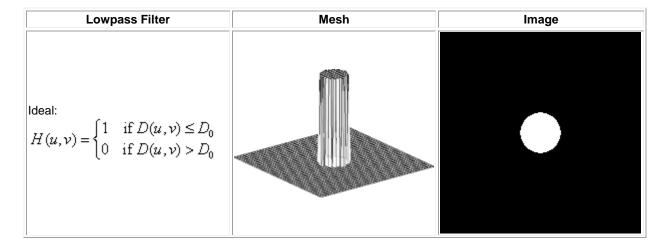
Lowpass filters:

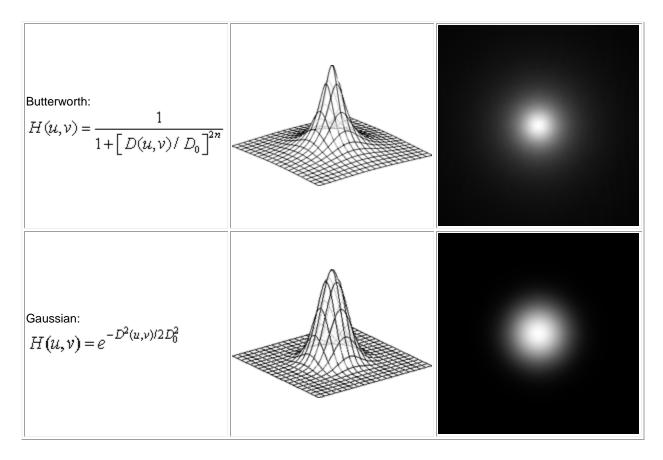
create a blurred (or smoothed) image attenuate the high frequencies and leave the low frequencies of the Fourier transform relatively unchanged

Three main lowpass filters are discussed in *Digital Image Processing Using MATLAB*:

- 1. ideal lowpass filter (ILPF)
- 2. Butterworth lowpass filter (BLPF)
- 3. Gaussian lowpass filter (GLPF)

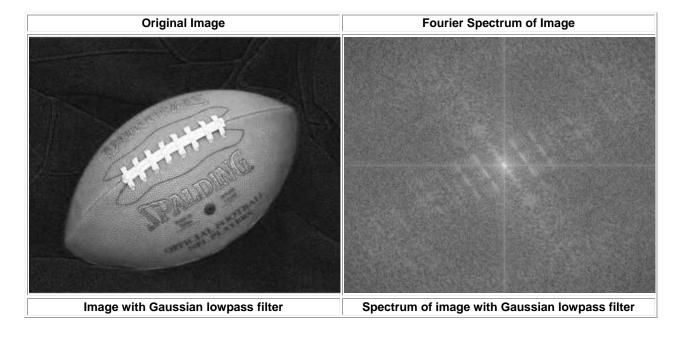
The corresponding formulas and visual representations of these filters are shown in the table below. In the formulae, D_0 is a specified nonnegative number. D(u,v) is the distance from point (u,v) to the center of the filter.

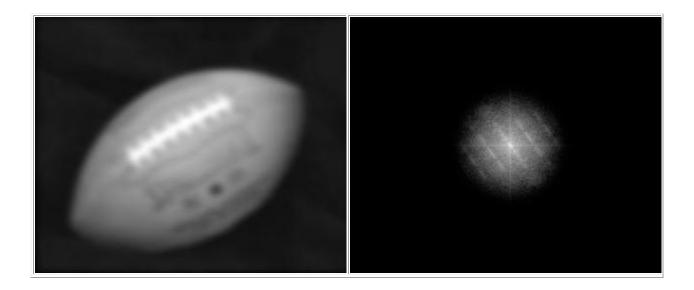




To view the MATLAB calls that were used to create the images in the above table, click on this link.

The following is the result of applying a Gaussian lowpass filter on an image.





The above images were created using three M-files (<u>paddedsize.m</u>, <u>lpfilter.m</u> and <u>dftuv.m</u>) and the following MATLAB calls:

```
footBall=imread('football.jpg');
%Convert to grayscale
footBall=rgb2gray(footBall);
imshow(footBall)
%Determine good padding for Fourier transform
PQ = paddedsize(size(footBall));
%Create a Gaussian Lowpass filter 5% the width of the Fourier transform
D0 = 0.05*PQ(1);
H = lpfilter('gaussian', PQ(1), PQ(2), D0);
% Calculate the discrete Fourier transform of the image
F=fft2(double(footBall), size(H,1), size(H,2));
% Apply the highpass filter to the Fourier spectrum of the image
LPFS football = H.*F;
% convert the result to the spacial domain.
LPF football=real(ifft2(LPFS football));
% Crop the image to undo padding
LPF football=LPF football(1:size(footBall,1), 1:size(footBall,2));
%Display the blurred image
figure, imshow(LPF football, [])
% Display the Fourier Spectrum
% Move the origin of the transform to the center of the frequency
rectangle.
Fc=fftshift(F);
Fcf=fftshift(LPFS football);
```

```
% use abs to compute the magnitude and use log to brighten display S1=log(1+abs(Fc)); S2=log(1+abs(Fcf)); figure, imshow(S1,[]) figure, imshow(S2,[])
```

3.2 Highpass Filters

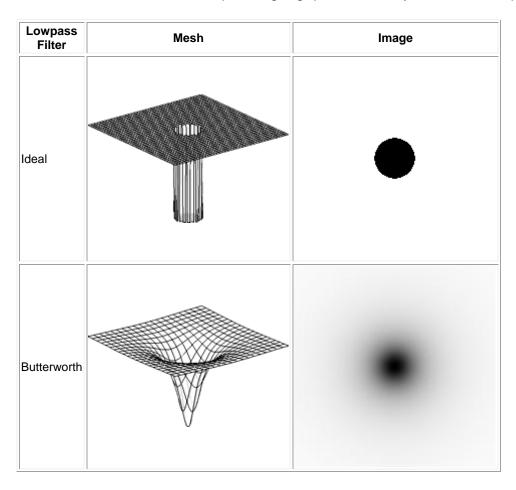
Highpass filters:

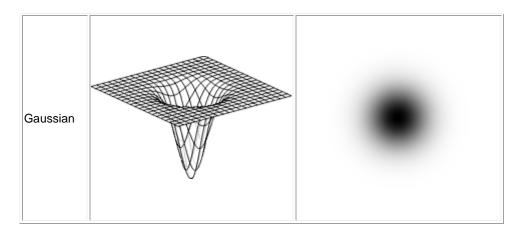
sharpen (or shows the edges of) an image attenuate the low frequencies and leave the high frequencies of the Fourier transform relatively unchanged

The highpass filter (H_{hp}) is often represented by its relationship to the lowpass filter (H_{lp}) :

$$H_{hp}(u,v) = 1 - H_{hp}(u,v)$$

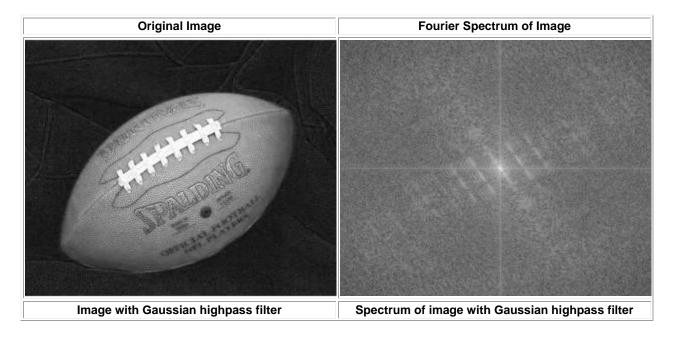
Because highpass filters can be created in relationship to lowpass filters, the following table shows the three corresponding highpass filters by their visual representations:

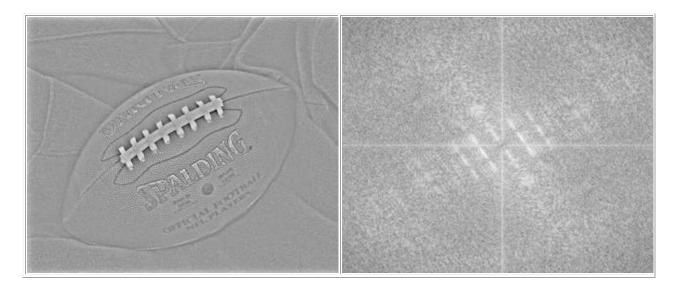




To view the MATLAB calls that were used to create the images in the above table, click on this link.

The following is the result of applying a Gaussian lowpass filter on an image.





The above images were created using four M-files (<u>paddedsize.m</u>, <u>dftuv.m</u>, and <u>hpfilter.m</u>) and the following MATLAB calls

```
footBall=imread('football.jpg');
%Convert to grayscale
footBall=rgb2gray(footBall);
imshow(footBall)
%Determine good padding for Fourier transform
PQ = paddedsize(size(footBall));
%Create a Gaussian Highpass filter 5% the width of the Fourier transform
D0 = 0.05*PQ(1);
H = hpfilter('gaussian', PQ(1), PQ(2), D0);
% Calculate the discrete Fourier transform of the image
F=fft2(double(footBall), size(H,1), size(H,2));
% Apply the highpass filter to the Fourier spectrum of the image
HPFS football = H.*F;
% convert the result to the spacial domain.
HPF_football=real(ifft2(HPFS football));
% Crop the image to undo padding
HPF football=HPF football(1:size(footBall,1), 1:size(footBall,2));
%Display the "Sharpened" image
figure, imshow(HPF_football, [])
% Display the Fourier Spectrum
% Move the origin of the transform to the center of the frequency
rectangle.
Fc=fftshift(F);
Fcf=fftshift(HPFS football);
% use abs to compute the magnitude and use log to brighten display
```

```
S1=log(1+abs(Fc));
S2=log(1+abs(Fcf));
figure, imshow(S1,[])
figure, imshow(S2,[])
```

3.3 Notch Filters

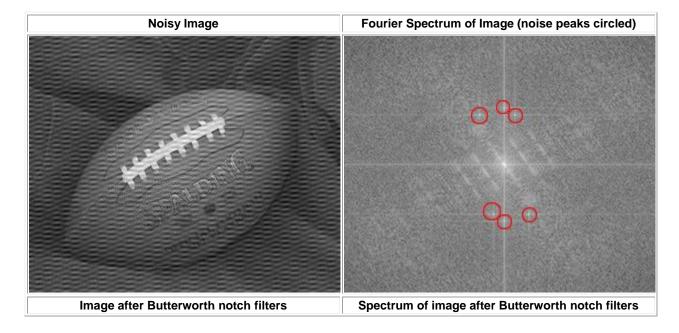
Notch filters:

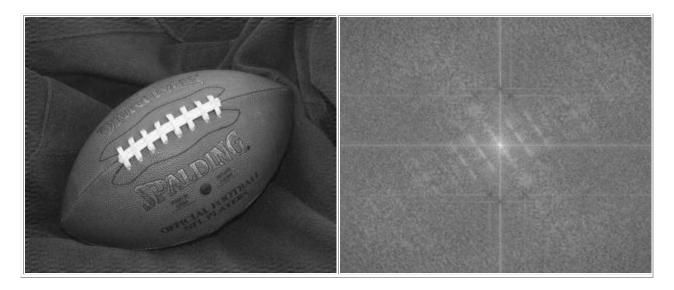
are used to remove repetitive "Spectral" noise from an image are like a narrow highpass filter, but they "notch" out frequencies other than the dc component

attenuate a selected frequency (and some of its neighbors) and leave other frequencies of the Fourier transform relatively unchanged

Repetitive noise in an image is sometimes seen as a bright peak somewhere other than the origin. You can suppress such noise effectively by carefully erasing the peaks. One way to do this is to use a notch filter to simply remove that frequency from the picture. This technique is very common in sound signal processing where it is used to remove mechanical or electronic hum, such as the 60Hz hum from AC power. Although it is possible to create notch filters for common noise patterns, in general notch filtering is an ad hoc procedure requiring a human expert to determine what frequencies need to be removed to clean up the signal.

The following is an example of removing synthetic spectral "noise" from an image.





The above images were created using four M-files (<u>paddedsize.m</u>, <u>lpfilter.m</u>, <u>dftuv.m</u>, and <u>notch.m</u>), <u>noiseball.png</u>, and the following MATLAB calls

```
footBall=imread('noiseball.png');
imshow(footBall)
%Determine good padding for Fourier transform
PQ = paddedsize(size(footBall));
%Create Notch filters corresponding to extra peaks in the Fourier
transform
H1 = notch('btw', PQ(1), PQ(2), 10, 50, 100);
H2 = notch('btw', PQ(1), PQ(2), 10, 1, 400);
H3 = notch('btw', PQ(1), PQ(2), 10, 620, 100);
H4 = notch('btw', PQ(1), PQ(2), 10, 22, 414);
H5 = notch('btw', PQ(1), PQ(2), 10, 592, 414);
H6 = notch('btw', PQ(1), PQ(2), 10, 1, 114);
% Calculate the discrete Fourier transform of the image
F=fft2 (double (footBall), PQ(1), PQ(2));
% Apply the notch filters to the Fourier spectrum of the image
FS football = F.*H1.*H2.*H3.*H4.*H5.*H6;
% convert the result to the spacial domain.
F football=real(ifft2(FS football));
% Crop the image to undo padding
F football=F football(1:size(footBall,1), 1:size(footBall,2));
%Display the blurred image
figure, imshow(F_football,[])
% Display the Fourier Spectrum
% Move the origin of the transform to the center of the frequency
rectangle.
Fc=fftshift(F);
```

```
Fcf=fftshift(FS_football);
% use abs to compute the magnitude and use log to brighten display
S1=log(1+abs(Fc));
S2=log(1+abs(Fcf));
figure, imshow(S1,[])
figure, imshow(S2,[])
```

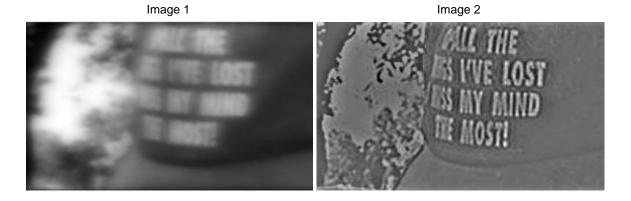
4. Exercises

Part 1: Identifying and Using High and Low Pass Filters (4 marks)

1. Download the following image "97.jpg" and store it in MATLAB's "Current Directory".



2. Identify which of the following is the result of a lowpass or highpass Butterworth filter and reproduce the results.



3. Display the Fourier spectrum for 97.jpg

Deliverables:

Identification of high and low pass filters in above images

Part 2: Using Spatial Filters in the Frequency Domain (4 marks)

1. Download the following image "two cats.jpg" and store it in MATLAB's "Current Directory".



- 2. Load the image data.
- 3. Create a spatial filter to get the horizontal edge of the image
- 4. Create a spatial filter to get the vertical edge of the image (read the MATLAB documentation of fspecial).
- 5. Transform both of these filters to the frequency domain.
- 6. Transform the two cats image to the frequency domain
- 7. Apply the appropriate operations in the frequency domain
- 8. Transform the data back into the spatial domain
- 9. Sum the horizontal and vertical edge components together
- 10. The resulting image should look like this:



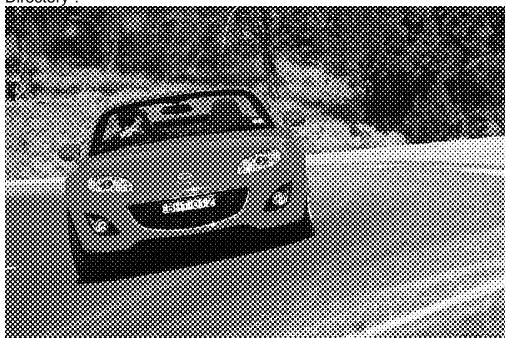
Deliverables:

image of horizontal edge image of vertical edge image of horizontal and vertical edge combined

Part 3: CSI Style Image Enhancement (4 marks)

You are the image processing expert for a local police department. A detective has reopened a cold case and part of his evidence is a newpaper print of a car. You have been asked to do some CSI style magic to see if you can learn the suspect's license plate number or see his face.

 Download the image "<u>halftone.png</u>" and store it in MATLAB's "Current Directory".



- 2. Use a set of notch filters to remove the peaks from the image's Fourier transform. **TIPS:**
 - o create a function that takes a list of peaks as an argument
 - o the peaks form a repetitive pattern. Figure out the pattern to save time.
- 3. Fine tune your results by trying varying widths of the three notch filter types. Provide a best effort solution for each one. Also provide a blurring based solution in Photoshop.

4. The following is one possible solution:



Deliverables:

A script that creates and displays 3 best effort notch filter sets for each of the three notch filter types.

Photoshop/Gimp created blur of the original image.

5. References

Digital Image Processing, Using MATLAB, by Rafael C. Gonzalez, Richard E. Woods, and Steven L. Eddins

Image Processing Toolbox, For Use with MATLAB (MATLAB's documentation)-available through MATLAB's help menu or online at:

http://www.mathworks.com/access/helpdesk/help/toolbox/images/